

10/6/21

Goal: Extend Composition to Calc 3

Calc I: $R \xrightarrow{f} R \xrightarrow{g} R = (g \circ f)(x)$

Calc III: $R^n \xrightarrow{F} R \quad R^n \xrightarrow{G} R$

Given $f: D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$ $f(x_1, x_2, \dots, x_n)$
 letting $g_i(x_1, x_2, \dots, x_n)$ for $1 \leq i \leq n$

WE CAN DEFINE COMPOSITION F OF G 's

$F(x_1, x_2, x_3, \dots, x_n) = g_1(x_1, x_2, x_3, \dots, x_n), g_2(x_1, x_2, x_3, \dots, x_n), \dots, g_n(x_1, x_2, x_3, \dots, x_n)$

EX: Suppose $f(x, y, z) = \cos(x+y)z^2 + 3$

$x(s, t) = s+t, y(s, t) = s \cdot t, z(s, t) = \cos(s)$

$f(x(s, t), y(s, t), z(s, t)) = \cos(s+t + s \cdot t) (\cos(s))^2 + 3$

$\begin{matrix} \mathbb{R}^k & \xrightarrow{g_1} \\ \mathbb{R}^k & \xrightarrow{g_2} \\ \mathbb{R}^k & \xrightarrow{g_3} \end{matrix} \quad \mathbb{R}^3 \xrightarrow{f} \mathbb{R}$

\searrow
 $\mathbb{R}^k \xrightarrow{G} \mathbb{R}^n \xrightarrow{F} \mathbb{R}$

Now to extend chain rule to Calc 3

Setup: Let $f(x, y)$ and $x(t), y(t)$ be differentiable functions.

*Def: A function $f: D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$ is differentiable at p when f is "well approximated" by a tangent hyper plane at p .
 ↳ As you get closer to p the error in approximating with the HYPER PLANE GOES TO 0.

↳ Now GIVEN f, x, y with $p = (a, b)$

$$f(x, y) = \underbrace{f(a, b)}_{\text{RHS}} + \underbrace{(f_x(a, b) + \epsilon_x(x, y))}_{\substack{\uparrow \text{change} \\ \text{in } x}} (x - a) + \underbrace{(f_y(a, b) + \epsilon_y(x, y))}_{\substack{\uparrow \text{error term for} \\ \text{change in } y}} (y - b)$$

$(\epsilon_x, \epsilon_y) \rightarrow (0, 0)$ as $(x, y) \rightarrow (a, b)$

$$\therefore f(x, y) - f(a, b) = (f_x(a, b)(x - a) + f_y(a, b)(y - b) + (\epsilon_x(x - a) + \epsilon_y(y - b)))$$

Choose a time α where $(x(\alpha), y(\alpha)) = p = (a, b)$
 Substituting into the formula we obtain

$$f(x(t), y(t)) - f(x(\alpha), y(\alpha)) = f_x(x(\alpha), y(\alpha))(x(t) - x(\alpha)) + f_y(x(\alpha), y(\alpha))(y(t) - y(\alpha)) + \epsilon_x(x(t) - x(\alpha)) + \epsilon_y(y(t) - y(\alpha))$$

For each $t \neq \alpha$ we divide by $t - \alpha$ to obtain



Let this expression be represented by Ω

$$\frac{f(x(\tau), y(\tau)) - f(x(\alpha), y(\alpha))}{\tau - \alpha} = f_x(x(\alpha), y(\alpha)) \left(\frac{x(\tau) - x(\alpha)}{\tau - \alpha} \right) + f_y(x(\alpha), y(\alpha)) \left(\frac{y(\tau) - y(\alpha)}{\tau - \alpha} \right) + \epsilon_x \left(\frac{x(\tau) - x(\alpha)}{\tau - \alpha} \right) + \epsilon_y \left(\frac{y(\tau) - y(\alpha)}{\tau - \alpha} \right)$$

Now limit it as $\tau \rightarrow \alpha$ we can understand the above as follows. Notice now this is just a case of derivative with respect to τ .

$$\lim_{\tau \rightarrow \alpha} \frac{f(x(\tau), y(\tau)) - f(x(\alpha), y(\alpha))}{\tau - \alpha}$$

$$f_x(x(\alpha), y(\alpha)) \lim_{\tau \rightarrow \alpha} \frac{x(\tau) - x(\alpha)}{\tau - \alpha}$$

$$+ f_y(x(\alpha), y(\alpha)) \lim_{\tau \rightarrow \alpha} \frac{y(\tau) - y(\alpha)}{\tau - \alpha}$$

$$+ \lim_{\tau \rightarrow \alpha} \epsilon_x \cdot \lim_{\tau \rightarrow \alpha} \frac{x(\tau) - x(\alpha)}{\tau - \alpha}$$

$$+ \lim_{\tau \rightarrow \alpha} \epsilon_y \cdot \lim_{\tau \rightarrow \alpha} \frac{y(\tau) - y(\alpha)}{\tau - \alpha}$$

$$= f_x(x(\alpha), y(\alpha)) x'(\alpha) + f_y(x(\alpha), y(\alpha)) y'(\alpha)$$

$$+ \lim_{\tau \rightarrow \alpha} \epsilon_x \cdot x'(\alpha) + \lim_{\tau \rightarrow \alpha} \epsilon_y \cdot y'(\alpha)$$

$\lim_{\tau \rightarrow \alpha} \epsilon_x = 0$ by our definition

$$\frac{d}{dx} f(x(\tau), y(\tau)) \Big|_p = f_x(x(\alpha), y(\alpha)) x'(\alpha) + f_y(x(\alpha), y(\alpha)) y'(\alpha)$$

Proposition Multivariate Chain Rule

Let $f(x_1, \dots, x_n)$ and $x_i(t_1, t_2, \dots, t_k)$ be differentiable for $1 \leq i \leq n$ then

* CAN
Cancel out
 $\frac{dx_i}{dt_j}$

$$\frac{\partial f}{\partial t_i} = \frac{\partial f}{\partial x_1} \cdot \frac{dx_1}{dt_j} + \frac{\partial f}{\partial x_2} \cdot \frac{dx_2}{dt_j} + \dots + \frac{\partial f}{\partial x_n} \cdot \frac{dx_n}{dt_j}$$

Partial Derivative
of f with respect
to the direction of x_i

Partial derivative
of the function
for x_i with respect
to a certain direction
 t_j . For single variable
functions we can only differentiate with respect
to one variable. Now we can do it with any t_j .

EX) Compute $\frac{\partial f}{\partial s}$, $\frac{\partial f}{\partial t}$

$$f(x, y) = e^x \sin(y)$$

$$x = s^2 t^2 \quad y = s^2 t$$

Solution 1: No chain rule.

$$f(x, y) = f(s^2 t^2, s^2 t)$$

$$= e^{s^2 t^2} \sin(s^2 t)$$

via product rule

$$\frac{\partial f}{\partial s} = 2t^2 e^{s^2 t^2} \sin(s^2 t) + 2st \cos(s^2 t) e^{s^2 t^2}$$

$$\frac{\partial f}{\partial t} = \frac{\partial}{\partial t} e^{s^2 t^2} \sin(s^2 t) + \frac{\partial}{\partial t} (\sin(s^2 t)) e^{s^2 t^2}$$

$$2ts e^{s^2 t^2} \sin(s^2 t) + s^2 \cos(s^2 t) e^{s^2 t^2}$$

* USING CHAIN RULE ONLY USUALLY MAKES THINGS EASIER

Solution 2: With Chain Rule

$$\frac{\partial f}{\partial s} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial s}$$

or

$$\frac{\partial f}{\partial t} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial t} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial t}$$

$$\frac{\partial f}{\partial x} = e^x \sin(y) \quad \frac{\partial f}{\partial y} = \cos(y) e^x$$

$$= e^{s^2} \sin(7s^2) \quad = \cos(7s^2) e^{4s^2}$$

$$\frac{dx}{ds} = 2s$$

$$\frac{dx}{dt} = 2st$$

$$\frac{dy}{ds} = 2st$$

$$\frac{dy}{dt} = s^2$$

$$\frac{\partial f}{\partial s} = e^{s^2} \sin(7s^2) \cdot 2s + e^{4s^2} \cos(7s^2) \cdot 2st$$

$$\frac{\partial f}{\partial t} = e^{s^2} \sin(7s^2) \cdot 2st + e^{4s^2} \cos(7s^2) \cdot s^2$$

let $f(x, y, z) = x^4 y + y^2 z^3$

$$x = r \sec \theta$$

$$y = r^2 e^{-t}$$

$$z = r^2 s \sin(\theta)$$

Compute

$$\frac{\partial f}{\partial r}$$

$$\frac{\partial f}{\partial s}$$

$$\frac{\partial f}{\partial t}$$

DO AT HOME

Recall Gen Calc 1.

Given an equation with both x and y

$(x-y)^2 = x+y^2$, you could compute
implicit derivatives of both sides

Implicit Function THEOREM? IFT

Let $F(x_1, x_2, \dots, x_n)$, differentiable, and
 $\frac{\partial F}{\partial x_i}$ be continuous on a disk about point p .
and $\frac{dF}{dx_n} \Big|_p \neq 0$ and $F(\vec{p}) = 0$

Back to where we are here of

$$(x-y)^2 = x+y^2 \rightarrow (x-y)^2 - x - y^2 = 0$$

\uparrow
 $F(\vec{p})$

Then $x_n = F(x_1, \dots, x_{n-1})$ for a point near p ,
is a separate function of the other variables
 $\frac{\partial F}{\partial x_i} = - \frac{\frac{dF}{dx_i}}{\frac{\partial F}{\partial x_n}}$